# COHOMOLOGY FOR FINITE INDEX INCLUSIONS OF FACTORS 

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#### Abstract

If $\mathcal{N} \subseteq \mathcal{M}$ is an inclusion of type $\mathrm{II}_{1}$ factors of finite index on a separable Hilbert space, and if $\mathcal{N}$ has a Cartan subalgebra then we show that $H^{n}(\mathcal{N}, \mathcal{M})=0$ for $n \geqslant 1$. We also show that $H_{\mathrm{cb}}^{n}(\mathcal{N}, \mathcal{M})=0, n \geqslant 1$, for an arbitrary finite index inclusion $\mathcal{N} \subseteq \mathcal{M}$ of von Neumann algebras. Keywords: von Neumann algebra, factor, Jones index, cohomology, Cartan subagebra, completely bounded, $C^{*}$-algebra.


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## 1. INTRODUCTION

The continuous Hochschild cohomology groups $H^{n}(\mathcal{N}, \mathcal{X})$ for a von Neumann algebra $\mathcal{N}$ and a Banach $\mathcal{N}$-bimodule $\mathcal{X}$ were first studied in a series of papers ([10], [11], [12], [15], [16]) by Johnson, Kadison and Ringrose. The primary focus was on the case $\mathcal{X}=\mathcal{N}$. The Kadison-Sakai theorem on derivations, [14], [24], had established that $H^{1}(\mathcal{N}, \mathcal{N})=0$ for all von Neumann algebras, and so it was natural to pose the question of whether $H^{n}(\mathcal{N}, \mathcal{N})=0$ for all $n \geqslant 2$. The work of [2], [4], [7], [15] on completely bounded cohomology gave an affirmative answer in the cases of type $\mathrm{I}, \mathrm{II}_{\infty}$ and III von Neumann algebras, as well as some classes of type $\mathrm{II}_{1}$ von Neumann algebras. However, the general type $\mathrm{II}_{1}$ case is still open.

In [26], [27] we were able to show that $H^{n}(\mathcal{N}, \mathcal{N})=0, n \geqslant 2$, for type $\mathrm{II}_{1}$ algebras with a separable predual and a Cartan subalgebra (a masa whose normalizing unitary group generates $\mathcal{N}$ as a von Neumann algebra). This is a rich class of von Neumann algebras ([9]), but algebras do exist without this property ([28]). The purpose of this paper is to extend these results (which built upon preliminary results in [3], [19]) to $H^{n}(\mathcal{N}, \mathcal{M}), n \geqslant 2$, where $\mathcal{N} \subseteq \mathcal{M}$ is an inclusion of type $\mathrm{II}_{1}$ factors of finite Jones index ([13], [22]). The case $n=1$ is already covered by a more general result of Christensen ([1]). It is important to consider more general modules in place of $\mathcal{N}$ itself. For example, Connes has shown that an
appropriate choice of module can distinguish between injective and non-injective von Neumann algebras ([8]; see also [6]). In a different direction, Kirchberg ([17]) has shown that the vanishing of $H^{1}(\mathcal{N}, B(H))$ is equivalent to a positive solution to the similarity problem for representations of $C^{*}$-algebras.

In the second section we establish some notation and recapitulate some standard theory for the reader's convenience. We also quote a theorem from [18] which we will used repeatedly. The third section is devoted to some preliminary results. One concerns the class of maps to which the averaging technique of [5] can be applied (Theorem 3.2), while another gives a method of estimating norms in $M_{n}(\mathcal{M})$ in the presence of Cartan subalgebras (Theorem 3.4). These are then applied in the last section to show that $H^{n}(\mathcal{N}, \mathcal{M})=0$ when $\mathcal{N}$ has a Cartan subalgebra and $\mathcal{N} \subseteq \mathcal{M}$ is an inclusion of factors of finite index. We also show that $H_{\mathrm{cb}}^{n}(\mathcal{N}, \mathcal{M})=\overline{0}$ for a finite index inclusion of von Neumann algebras.

We refer the reader to [23], [25] for general background on cohomology, and to [26], [27] for many of the techniques which we draw on here. However, we have taken the opportunity to streamline some of the arguments and the introduction of $*$-automorphisms in Corollary 3.5 is a useful suggestion of Florin Pop.

## 2. PRELIMINARIES

A bounded map $\varphi: \mathcal{E} \rightarrow \mathcal{F}$ between operator spaces lifts naturally to a bounded $\operatorname{map} \varphi^{(k)}: M_{k}(\mathcal{E}) \rightarrow M_{k}(\mathcal{F})$ on the $k \times k$ matrices over $\mathcal{E}$ for each $k \geqslant 1\left(\varphi_{k}\right.$ is a more standard notation for this map but we reserve this for a different purpose). Then $\varphi$ is completely bounded if the quantity

$$
\begin{equation*}
\|\varphi\|_{\mathrm{cb}} \equiv \sup \left\{\left\|\varphi^{(k)}\right\|: k \geqslant 1\right\} \tag{2.1}
\end{equation*}
$$

is finite. If square matrices are replaced by the spaces $\operatorname{Row}_{k}(\mathcal{E})$ of rows over $\mathcal{E}$ of length $k$, then the corresponding supremum in (2.1) defines the row bounded norm. The inequalities

$$
\begin{equation*}
\|\varphi\| \leqslant\|\varphi\|_{\mathrm{r}} \leqslant\|\varphi\|_{\mathrm{cb}} \tag{2.2}
\end{equation*}
$$

are immediate from the definitions, and the interplay between these three norms is crucial for the results of this paper. We will denote by $\operatorname{CB}(\mathcal{E}, \mathcal{F})$ and $\operatorname{RB}(\mathcal{E}, \mathcal{F})$ respectively the spaces of completely bounded and row bounded maps from $\mathcal{E}$ to $\mathcal{F}$.

For an inclusion $\mathcal{N} \subseteq \mathcal{M}$ of von Neumann or $C^{*}$-algebras we denote by $\mathcal{L}^{n}(\mathcal{N}, \mathcal{M})$ the space of $n$-linear bounded maps $\varphi: \mathcal{N}^{n} \rightarrow \mathcal{M}$. The coboundary operator $\partial: \mathcal{L}^{n}(\mathcal{N}, \mathcal{M}) \rightarrow \mathcal{L}^{n+1}(\mathcal{N}, \mathcal{M})$ is defined by

$$
\begin{align*}
\partial \varphi\left(x_{1}, \ldots, x_{n+1}\right)= & x_{1} \varphi\left(x_{2}, \ldots, x_{n+1}\right) \\
& +\sum_{i=1}^{n}(-1)^{i} \varphi\left(x_{1}, \ldots, x_{i-1}, x_{i} x_{i+1}, x_{i+2}, \ldots, x_{n+1}\right)  \tag{2.3}\\
& +(-1)^{n+1} \varphi\left(x_{1}, \ldots, x_{n}\right) x_{n+1}
\end{align*}
$$

for $x_{i} \in \mathcal{N}$. Then $\varphi$ is an $n$-cocycle if $\partial \varphi=0$, while $\varphi$ is said to be an $n$-coboundary if there exists $\psi \in \mathcal{L}^{n-1}(\mathcal{N}, \mathcal{M})$ such that $\varphi=\partial \psi$. A short algebraic calculation shows that $\partial \partial=0$ and so coboundaries are cocycles. For $n \geqslant 2$ the cohomology
group $H^{n}(\mathcal{N}, \mathcal{M})$ is defined to be the space of $n$-cocycles modulo the space of $n$ coboundaries. For $n=1, H^{1}(\mathcal{N}, \mathcal{M})$ is the space of derivations modulo the space of inner derivations. The coefficient space $\mathcal{M}$ could be replaced by any Banach $\mathcal{N}$-bimodule in these definitions.

We will focus on von Neumann factors $\mathcal{N}$ of type $\mathrm{II}_{1}$ with Cartan subalgebras $\mathcal{A}$ : the defining property is that $\mathcal{A}$ is a maximal abelian self-adjoint subalgebra of $\mathcal{N}$ whose normalizing unitary group $\mathcal{U} \subseteq \mathcal{N}$ generates $\mathcal{N}$ as a von Neumann algebra. Here $\mathcal{U}$ is the set of unitaries $u \in \mathcal{N}$ such that $u \mathcal{A} u^{*}=\mathcal{A}$. We will also be interested in the case when $\mathcal{N}$ has finite Jones index [ $\mathcal{M}: \mathcal{N}]$ in $\mathcal{M}$ ([13], [22]). For such inclusions a result of Pimsner and Popa ([18]) to the effect that $\mathcal{M}$ is finitely generated as both a left and right $\mathcal{N}$-module will be important. Since we will use it repeatedly, we state it here.

Theorem 2.1. ([18]) Let $\mathcal{N} \subseteq \mathcal{M}$ be an inclusion of type $\mathrm{II}_{1}$ factors with $[\mathcal{M}: \mathcal{N}]<\infty$. Write $[\mathcal{M}: \mathcal{N}]=n+\alpha$ ( $n$ an integer and $0 \leqslant \alpha<1$ ), and let $E_{\mathcal{N}}$ be the trace preserving conditional expectation of $\mathcal{M}$ onto $\mathcal{N}$. Then there exist $m_{1}, \ldots, m_{n+1} \in \mathcal{M}$ and a projection $p \in \mathcal{N}$ of trace $\alpha$ with the following properties:
(i) $\mathcal{M}=\mathcal{N} m_{1}+\mathcal{N} m_{2}+\cdots+\mathcal{N} m_{n}+\mathcal{N} p m_{n+1}$;
(ii) $E_{\mathcal{N}}\left(m_{j} m_{k}^{*}\right)=0$ for $j \neq k$;
(iii) $E_{\mathcal{N}}\left(m_{j} m_{j}^{*}\right)=1$ for $1 \leqslant j \leqslant n$;
(iv) $E_{\mathcal{N}}\left(m_{n+1} m_{n+1}^{*}\right)=p$;
(v) $\left\|m_{j}\right\| \leqslant[\mathcal{M}: \mathcal{N}]^{1 / 2}, 1 \leqslant j \leqslant n+1$;
(vi) $\mathcal{M}=m_{1}^{*} \mathcal{N}+m_{2}^{*} \mathcal{N}+\cdots+m_{n}^{*} \mathcal{N}+m_{n+1}^{*} p \mathcal{N}$.

Properties (i)-(v) are the original formulation but (vi) follows from (i) by taking adjoints. We will use both the left and right $\mathcal{N}$-module decompositions of $\mathcal{M}$ subsequently. We note for future reference that properties (ii)-(iv) ensure that the $\mathcal{N}$-coefficients of an expansion of $m \in \mathcal{M}$ by (i) are unique. For example, if $x \in \mathcal{N}$ and $x m_{1}=0$ then

$$
x=E_{\mathcal{N}}\left(x m_{1} m_{1}^{*}\right)=0
$$

using (iii) and the $\mathcal{N}$-linearity of $E_{\mathcal{N}}$.

## 3. AVERAGING MAPS

In this section we extend a result from [6] on the averaging of elements in $\mathrm{CB}(\mathcal{N}, \mathcal{N})$ to a larger class of maps $\mathcal{S} \subseteq \operatorname{RB}(\mathcal{N}, B(H))$. While we do not have a characterization of which row bounded maps lie in $\mathcal{S}$, we will be able to show that this set does contain all maps used subsequently, and this is sufficient for our purposes.

Let $n_{1}, \ldots, n_{k} \in \mathcal{N}$ be fixed elements satisfying $\sum_{i=1}^{k} n_{i}^{*} n_{i} \leqslant 1$, and define $\beta: \operatorname{RB}(\mathcal{N}, B(H)) \rightarrow \mathrm{RB}(\mathcal{N}, B(H))$ by

$$
\begin{equation*}
(\beta \varphi)(x)=\sum_{i=1}^{k} \varphi\left(x n_{i}^{*}\right) n_{i} \tag{3.1}
\end{equation*}
$$

for $x \in \mathcal{N}$ and $\varphi \in \operatorname{RB}(\mathcal{N}, B(H))$.

Lemma 3.1. The map $\beta$ is a contraction in the row bounded norm.
Proof. Fix $\varphi \in \operatorname{RB}(\mathcal{N}, B(H))$ and let $\psi=\beta \varphi$. If $R=\left(x_{1}, \ldots, x_{j}\right) \in$ $\operatorname{Row}_{j}(\mathcal{N}),\|R\|=1$, then let $\widetilde{R} \in \operatorname{Row}_{j k}(\mathcal{N})$ be the row

$$
\left(x_{1} n_{1}^{*}, \ldots, x_{1} n_{k}^{*}, \ldots, x_{j} n_{1}^{*}, \ldots, x_{j} n_{k}^{*}\right)
$$

Then

$$
\begin{equation*}
\widetilde{R} \widetilde{R}^{*}=\sum_{l=1}^{j} \sum_{i=1}^{k} x_{l} n_{i}^{*} n_{i} x_{l}^{*} \leqslant \sum_{l=1}^{j} x_{l} x_{l}^{*} \tag{3.2}
\end{equation*}
$$

so

$$
\begin{equation*}
\|\widetilde{R}\| \leqslant\|R\|=1 \tag{3.3}
\end{equation*}
$$

Now form the $j k \times j$ matrix

$$
A=\left(\begin{array}{cccc}
C & \theta & & \theta  \tag{3.4}\\
\theta & C & & \vdots \\
\theta & \theta & \ddots & \theta \\
\theta & \theta & & C
\end{array}\right)
$$

where $\theta$ denotes a column of $k 0$ 's and $C^{*}=\left(n_{1}^{*}, \ldots, n_{k}^{*}\right)$. Then $A^{*} A \in M_{j}(\mathcal{N})$ is diagonal and each diagonal entry is $C^{*} C$. Thus $\|A\| \leqslant 1$. A short calculation shows that

$$
\begin{equation*}
\psi^{(j)}(R)=\varphi^{(j k)}(\widetilde{R}) A \tag{3.5}
\end{equation*}
$$

and it follows from (3.3) that

$$
\begin{equation*}
\left\|\psi^{(j)}(R)\right\| \leqslant\|\varphi\|_{\mathrm{r}}\|\widetilde{R}\|\|A\| \leqslant\|\varphi\|_{\mathrm{r}} \tag{3.6}
\end{equation*}
$$

Since $R$ was an arbitrary row of unit norm, (3.6) shows that $\|\psi\|_{\mathrm{r}} \leqslant\|\varphi\|_{\mathrm{r}}$ and $\beta$ is a contraction in the row bounded norm.

In [6] the existence of a projection $\rho: \mathrm{CB}(\mathcal{N}, \mathcal{N}) \rightarrow \mathrm{CB}(\mathcal{N}, \mathcal{N})_{\mathcal{N}}$ (the subspace of right $\mathcal{N}$-modular maps) was established for any von Neumann algebra $\mathcal{N}$, and moreover $\rho$ was the point ultraweak limit of a net of maps $\rho_{\alpha}: \mathrm{CB}(\mathcal{N}, \mathcal{N}) \rightarrow$ $\operatorname{CB}(\mathcal{N}, \mathcal{N})$ where each $\rho_{\alpha}$ had the form

$$
\begin{equation*}
\left(\rho_{\alpha} \varphi\right)(x)=\sum_{j=1}^{\infty} \varphi\left(x n_{j \alpha}^{*}\right) n_{j \alpha}, \quad x \in \mathcal{N} \tag{3.7}
\end{equation*}
$$

where $\varphi \in \mathrm{CB}(\mathcal{N}, \mathcal{N}), n_{j \alpha} \in \mathcal{N}$, and $\sum_{j=1}^{\infty} n_{j \alpha}^{*} n_{j \alpha}=1$. A simple pointwise ultraweak limit argument establishes Lemma 3.1 for infinite sums, and so equation (3.7) extends the definition of $\rho_{\alpha}$ to a contraction (in the row bounded norm) of $\operatorname{RB}(\mathcal{N}, B(H))$ to itself. While $\rho$ and its approximating net need not be unique, we fix one such collection for the subsequent discussion. It is not clear that the net of $\rho_{\alpha}$ 's on the larger space of maps converges in any topology. To remedy this, we introduce an intermediate domain defined by convergence of the net not only to a limit, but to one of a particular kind. Specifically, we form the subset $\mathcal{S}$ of
$\operatorname{RB}(\mathcal{N}, B(H))$ defined by the following property: $\varphi \in \mathcal{S}$ if there exists an operator $t \in B(H)$ such that

$$
\begin{equation*}
\lim _{\alpha}\left(\rho_{\alpha} \varphi\right)(x)=t x \tag{3.8}
\end{equation*}
$$

ultraweakly for $x \in \mathcal{N}$. We then let $\rho \varphi$ be the point ultraweak limit of $\rho_{\alpha} \varphi$ for $\varphi \in \mathcal{S}$. Since this domain is defined abstractly, we will have to show subsequently that it contains all maps of interest to us.

We note that $\mathrm{RB}(\mathcal{N}, B(H))$ is a $(B(H), \mathcal{N})$-bimodule under the following left and right actions:

$$
\begin{align*}
& (t \varphi)(x)=t \varphi(x), \quad x \in \mathcal{N}, t \in B(H),  \tag{3.9}\\
& \varphi_{y}(x)=\varphi(y x), \quad x, y \in \mathcal{N}, \tag{3.10}
\end{align*}
$$

for $\varphi \in \operatorname{RB}(\mathcal{N}, B(H))$.
Theorem 3.2. For any von Neumann algebra $\mathcal{N} \subseteq B(H)$ :
(i) $\mathcal{S}$ is a norm closed $(B(H), \mathcal{N})$-submodule of $\overline{\mathrm{R}} \mathrm{B}(\mathcal{N}, B(H))$ containing $\operatorname{CB}(\mathcal{N}, \mathcal{N})$;
(ii) If $\varphi \in \mathcal{S}, t \in B(H), y \in \mathcal{N}$ then

$$
\begin{equation*}
\rho(t \varphi)=t(\rho \varphi), \quad \rho \varphi_{y}=(\rho \varphi)_{y} \tag{3.11}
\end{equation*}
$$

(iii) $\rho$ is a contraction in the row bounded norm;
(iv) If $\varphi \in \mathcal{S}$ and has range in a von Neumann algebra $\mathcal{M}$ containing $\mathcal{N}$ then there exists $m \in \mathcal{M}$ such that, for $x \in \mathcal{N}$,

$$
\begin{equation*}
\rho \varphi(x)=m x, \quad\|m\| \leqslant\|\varphi\|_{\mathrm{r}} . \tag{3.12}
\end{equation*}
$$

Moreover, if $\mathcal{N} \subseteq \mathcal{M} \subseteq B(H)$ is an inclusion of type $\mathrm{II}_{1}$ factors of finite index then
(v) $\mathcal{S}$ contains $\operatorname{CB}(\mathcal{N}, \mathcal{M})$.

Proof. That $\mathcal{S}$ contains $\operatorname{CB}(\mathcal{N}, \mathcal{N})$ is the original version of this theorem ([6]). Part (iii) follows from Lemma 3.1 which establishes the contractivity of each $\rho_{\alpha}$ by a simple limit argument. It is then easy to see that $\mathcal{S}$ is a norm closed subspace of $\mathrm{RB}(\mathcal{N}, B(H))$.

From (3.7), each $\rho_{\alpha}$ commutes with the left and right module actions of $B(H)$ and $\mathcal{N}$ respectively, and thus so does $\rho$. The remaining parts of (i) and (ii) are then immediate.

If $\varphi \in \mathcal{S}$ has range in $\mathcal{M} \supseteq \mathcal{N}$ then the same is true for each $\rho_{\alpha} \varphi$, by (3.7), and also for $\rho \varphi$ by taking ultraweak limits. Putting $x=1$ in (3.8) establishes (3.12).

Now suppose that $\mathcal{N} \subseteq \mathcal{M} \subseteq B(H)$ is an inclusion of type $\mathrm{II}_{1}$ factors with $[\mathcal{M}: \mathcal{N}]<\infty$. By Theorem 2.1 we may write

$$
\begin{equation*}
\mathcal{M}=m_{1}^{*} \mathcal{N}+\cdots+m_{n}^{*} \mathcal{N}+m_{n+1}^{*} p \mathcal{N} \tag{3.13}
\end{equation*}
$$

If $\varphi \in \mathrm{CB}(\mathcal{N}, \mathcal{M})$ then define $\varphi_{i} \in \mathrm{CB}(\mathcal{N}, \mathcal{N}), 1 \leqslant i \leqslant n+1$, by

$$
\begin{equation*}
\varphi_{i}(x)=E_{\mathcal{N}}\left(m_{i} \varphi(x)\right), \quad x \in \mathcal{N} \tag{3.14}
\end{equation*}
$$

Fix $x \in \mathcal{N}$. By (3.13) there exist $y_{1}, \ldots, y_{n+1} \in \mathcal{N}$ such that

$$
\begin{equation*}
\varphi(x)=m_{1}^{*} y_{1}+\cdots+m_{n}^{*} y_{n}+m_{n+1}^{*} p y_{n+1} \tag{3.15}
\end{equation*}
$$

Multiply (3.15) by $m_{i}$ and apply $E_{\mathcal{N}}$ to obtain

$$
\begin{align*}
& E_{\mathcal{N}}\left(m_{i} \varphi(x)\right)=y_{i}, \quad 1 \leqslant i \leqslant n  \tag{3.16}\\
& E_{\mathcal{N}}\left(m_{n+1} \varphi(x)\right)=p y_{n+1} \tag{3.17}
\end{align*}
$$

It follows from (3.14)-(3.17) that

$$
\begin{equation*}
\varphi(x)=m_{1}^{*} \varphi_{1}(x)+\cdots+m_{n+1}^{*} \varphi_{n+1}(x), \quad x \in \mathcal{N} \tag{3.18}
\end{equation*}
$$

By the module properties of (i), we see that $\varphi \in \mathcal{S}$, completing the proof.
The notion of finite index inclusions of type $\mathrm{II}_{1}$ factors can be extended to general inclusions in the following way ([22]). An inclusion $\mathcal{N} \subseteq \mathcal{M}$ of von Neumann algebras is said to be of finite index if there exists a conditional expectation $E: \mathcal{M} \rightarrow \mathcal{N}$ and a constant $c>0$ such that $E(x) \geqslant c x$ for all $x \in \mathcal{M}^{+}$. As noted in 1.1.2 of [22], such a conditional expectation is automatically normal. In this more general situation we may obtain a projection of $\mathrm{CB}(\mathcal{N}, \mathcal{M})$ onto the space $\mathrm{CB}(\mathcal{N}, \mathcal{M})_{\mathcal{N}}$ of completely bounded right $\mathcal{N}$-module maps.

Theorem 3.3. Let $\mathcal{N} \subseteq \mathcal{M}$ be a finite index inclusion of von Neumann algebras. Then there exists a contractive projection $\rho: \mathrm{CB}(\mathcal{N}, \mathcal{M}) \rightarrow \mathrm{CB}(\mathcal{N}, \mathcal{M})_{\mathcal{N}}$ which is the point ultraweak limit of maps $\rho_{\alpha}$ of the form (3.7). Moreover, $\rho$ satisfies

$$
\begin{equation*}
\rho(m \varphi)=m(\rho \varphi), \quad \rho \varphi_{y}=(\rho \varphi)_{y} \tag{3.19}
\end{equation*}
$$

for $\varphi \in \mathrm{CB}(\mathcal{N}, \mathcal{M}), m \in \mathcal{M}$ and $y \in \mathcal{N}$.
Proof. By [5], there is a projection $\rho: \mathrm{CB}(\mathcal{N}, \mathcal{N}) \rightarrow \mathrm{CB}(\mathcal{N}, \mathcal{N})_{\mathcal{N}}$ which is the point ultraweak limit of maps $\rho_{\alpha}$ of the form (3.7). Each $\rho_{\alpha}$ has an obvious extension to a map of $\operatorname{CB}(\mathcal{N}, \mathcal{M})$ to itself, which we also denote by $\rho_{\alpha}$. By compactness, we may drop to a subnet and assume that $\lim _{\alpha}\left(\rho_{\alpha} \varphi\right)(x)$ exists ultraweakly (in $\mathcal{M})$ for $\varphi \in \mathrm{CB}(\mathcal{N}, \mathcal{M})$ and $x \in \mathcal{N}$. This limit then defines a contraction $\rho: \mathrm{CB}(\mathcal{N}, \mathcal{M}) \rightarrow \mathrm{CB}(\mathcal{N}, \mathcal{M})$, extending the one originally defined on $\operatorname{CB}(\mathcal{N}, \mathcal{N})$. The relations (3.19) are immediate from the definition of the $\rho_{\alpha}$ 's, after taking point ultraweak limits. Each $\rho_{\alpha}$ leaves fixed every right $\mathcal{N}$-module map and the same is then true of $\rho$. It thus suffices to show that the range of $\rho$ is $\mathrm{CB}(\mathcal{N}, \mathcal{M})_{\mathcal{N}}$. By hypothesis there is a constant $c>0$ and a normal conditional expectation $E: \mathcal{M} \rightarrow \mathcal{N}$ such that $E(x) \geqslant c x$ for $x \in \mathcal{M}^{+}$. We note that $E$ is $\mathcal{N}$-bimodular. For $\varphi \in \operatorname{CB}(\mathcal{N}, \mathcal{M})$ and $x \in \mathcal{N}$, it follows that

$$
\begin{aligned}
\rho_{\alpha}(E \varphi)(x) & =\sum_{j=1}^{\infty}(E \varphi)\left(x n_{j \alpha}^{*}\right) n_{j \alpha}=\sum_{j=1}^{\infty} E\left(\varphi\left(x n_{j \alpha}^{*}\right)\right) n_{j \alpha} \\
& =E\left(\sum_{j=1}^{\infty} \varphi\left(x n_{j \alpha}^{*}\right) n_{j \alpha}\right)=E\left(\left(\rho_{\alpha} \varphi\right)(x)\right),
\end{aligned}
$$

and taking the limit over $\alpha$ (once again using normality of $E$ ) gives

$$
\begin{equation*}
\rho(E \varphi)=E(\rho \varphi) \tag{3.20}
\end{equation*}
$$

Now fix $\varphi \in \operatorname{CB}(\mathcal{N}, \mathcal{M}), n \in \mathcal{N}$, and a projection $e \in \mathcal{N}$, and define $b=$ $(\rho \varphi)(n(1-e)) e$. Then define $\psi \in \operatorname{CB}(\mathcal{N}, \mathcal{M})$ by

$$
\begin{equation*}
\psi(x)=b^{*} \varphi(x), \quad x \in \mathcal{N} \tag{3.21}
\end{equation*}
$$

Since $E \psi \in \mathrm{CB}(\mathcal{N}, \mathcal{M}), \rho(E \psi)$ is a right $\mathcal{N}$-module map, and so also is $E(\rho \psi)$ by (3.20). Hence

$$
\begin{align*}
E\left(b^{*} \rho \varphi(x(1-e)) e\right) & =(E \rho)\left(b^{*} \varphi\right)(x(1-e)) e=(E \rho \psi)(x(1-e)) e \\
& =(E \rho \psi)(x(1-e) e)=0 \tag{3.22}
\end{align*}
$$

for $x \in \mathcal{N}$. Putting $x=n$ in (3.22) gives $E\left(b^{*} b\right)=0$, and so we conclude that $b=0$ from the inequalities

$$
0 \leqslant b^{*} b \leqslant c^{-1} E\left(b^{*} b\right)=0
$$

Since $n$ and $e$ were arbitrary, it follows that $(\rho \varphi)(x(1-e)) e=0$ for $x \in \mathcal{N}$ and any projection $e \in \mathcal{N}$. Thus

$$
\begin{align*}
(\rho \varphi)(x) e-\rho \varphi(x e) & =\rho \varphi(x e+x(1-e)) e-\rho \varphi(x e)=\rho \varphi(x e) e-\rho \varphi(x e)  \tag{3.23}\\
& =-\rho \varphi(x e)(1-e)=0
\end{align*}
$$

because $1-e$ is also a projection in $\mathcal{N}$. Since $\mathcal{N}$ is the norm closed span of its projections, right $\mathcal{N}$-modularity of $\rho \varphi$ follows from (3.23).

The next result provides a method of estimating norms in matrix algebras over a von Neumann algebra.

Theorem 3.4. Let $\mathcal{N} \subseteq \mathcal{M}$ be an inclusion of type $\mathrm{II}_{1}$ factors of finite index, and suppose that $\mathcal{N}$ has a Cartan subalgebra $\mathcal{A}$. Then there exists a constant $c\left(=2[\mathcal{M}: \mathcal{N}]^{2}\right)$ such that, for $X \in M_{k}(\mathcal{M}), k \geqslant 1$,

$$
\|X\| \leqslant c \sup \left\{\|R X\|: R \in \operatorname{Row}_{k}(\mathcal{A}),\|R\| \leqslant 1\right\}
$$

Proof. Fix $X \in M_{k}(\mathcal{M}),\|X\|=1$. By Theorem 2.1 there exist matrices $Y_{i} \in M_{k}(\mathcal{N})$ such that

$$
\begin{equation*}
X=Y_{1} W_{1}+\cdots+Y_{n} W_{n}+Y_{n+1} P W_{n+1} \tag{3.24}
\end{equation*}
$$

where $W_{i}$ is the $k \times k$ diagonal matrix with $m_{i}$ on the diagonal and $P$ is the $k \times k$ diagonal matrix with $p$ on the diagonal. By the triangle inequality, we may assume without loss of generality that $\left\|Y_{1} W_{1}\right\| \geqslant 1 /(n+1)$ (the case $\left\|Y_{n+1} P W_{n+1}\right\| \geqslant$ $1 /(n+1)$ is similar). Since $\left\|m_{1}\right\| \leqslant[\mathcal{M}: \mathcal{N}]^{1 / 2}$, it follows that

$$
\left\|Y_{1}\right\| \geqslant[\mathcal{M}: \mathcal{N}]^{-1 / 2}(n+1)^{-1}
$$

Given $\varepsilon>0$ we may find, by [27], $\operatorname{Proposition~} 4.1, R \in \operatorname{Row}_{k}(\mathcal{A}),\|R\|=1$, such that

$$
\begin{equation*}
\left\|R Y_{1}\right\| \geqslant(1-\varepsilon)\left\|Y_{1}\right\| \tag{3.25}
\end{equation*}
$$

Then multiply (3.24) on the left by $R$, on the right by $W_{1}^{*}$, and apply

$$
E_{\mathcal{N} \otimes M_{k}}=E_{\mathcal{N}} \otimes I_{k}
$$

to obtain

$$
\begin{equation*}
R Y_{1}=E_{\mathcal{N} \otimes M_{k}}\left(R X W_{1}^{*}\right) \tag{3.26}
\end{equation*}
$$

Since $E_{\mathcal{N} \otimes M_{k}}$ is completely positive and unital, it follows that
(3.27) $\quad\left\|R Y_{1}\right\| \leqslant\left\|R X W_{1}^{*}\right\| \leqslant\|R X\|\left\|W_{1}^{*}\right\|=\|R X\|\left\|m_{1}\right\| \leqslant\|R X\|[\mathcal{M}: \mathcal{N}]^{1 / 2}$.

The previous estimates then combine to give

$$
\begin{align*}
\|R X\| & \geqslant[\mathcal{M}: \mathcal{N}]^{-1 / 2}\left\|R Y_{1}\right\| \geqslant[\mathcal{M}: \mathcal{N}]^{-1 / 2}(1-\varepsilon)\left\|Y_{1}\right\| \\
& \geqslant(1-\varepsilon)[\mathcal{M}: \mathcal{N}]^{-1}(n+1)^{-1} \tag{3.28}
\end{align*}
$$

Since $\varepsilon>0$ was arbitrary, and $n+1 \leqslant 2[\mathcal{M}: \mathcal{N}]$, the result follows from (3.28), where $c$ may be taken to be $2[\mathcal{M}: \mathcal{N}]^{2}$.

The next result appears to be very specialized, but will be needed in the next section.

Corollary 3.5. Let $\mathcal{N} \subseteq \mathcal{M}$ be an inclusion of type $\mathrm{II}_{1}$ factors with finite index, where $\mathcal{N}$ has a Cartan subalgebra $\mathcal{A}$. Let $\mu: \mathcal{N} \rightarrow \mathcal{M}$ be row bounded and suppose that there is a *-automorphism $\alpha$ of $\mathcal{A}$ such that

$$
\begin{equation*}
a \mu(x)=\mu(\alpha(a) x), \quad a \in \mathcal{A}, x \in \mathcal{N} \tag{3.29}
\end{equation*}
$$

Then $\mu$ is completely bounded and

$$
\begin{equation*}
\|\mu\|_{\mathrm{cb}} \leqslant\left(2[\mathcal{M}: \mathcal{N}]^{2}\right)\|\mu\|_{\mathrm{r}} \tag{3.30}
\end{equation*}
$$

Proof. Fix $k \geqslant 1$, and consider $X \in M_{k}(\mathcal{N}),\|X\|=1$. The automorphism $\alpha^{(k)}$ of $M_{k}(\mathcal{A})$ maps $\operatorname{Row}_{k}(\mathcal{A})$ isometrically onto itself, and thus, by Theorem 3.4,

$$
\begin{align*}
\left\|\mu^{(k)}(X)\right\| & \leqslant 2[\mathcal{M}: \mathcal{N}]^{2} \sup \left\{\left\|R \mu^{(k)}(X)\right\|: R \in \operatorname{Row}_{k}(\mathcal{A}),\|R\|=1\right\} \\
& =2[\mathcal{M}: \mathcal{N}]^{2} \sup \left\{\left\|\mu^{(k)}\left(\alpha^{(k)}(R) X\right)\right\|: R \in \operatorname{Row}_{k}(\mathcal{A}),\|R\|=1\right\}  \tag{3.31}\\
& \leqslant 2[\mathcal{M}: \mathcal{N}]^{2}\|\mu\|_{\mathrm{r}}
\end{align*}
$$

since the second supremum is calculated by applying $\mu$ to rows. Since $k \geqslant 1$ was arbitrary, we have established (3.30).

## 4. THE MAIN RESULTS

For the first result we will assume that $\mathcal{N} \subseteq \mathcal{M}$ is an inclusion of type $I_{1}$ factors of finite index represented on the Hilbert space $L^{2}(\mathcal{M}, \operatorname{tr})$ which we assume to be separable (or equivalently, $\mathcal{N}$ has separable predual). We also assume that $\mathcal{N}$ has a Cartan subalgebra $\mathcal{A}$, whereupon we can find a hyperfinite factor $\mathcal{R}$ such that $\mathcal{A} \subseteq \mathcal{R} \subseteq \mathcal{N}$ and $\mathcal{R}^{\prime} \cap \mathcal{N}=\mathbb{C} 1$ ([20]). Christensen ([1]) has shown that $H^{1}(\mathcal{N}, \overline{\mathcal{M}})=0$ for any inclusion $\mathcal{N} \subseteq \mathcal{M}$ of finite von Neumann algebras. Thus our examination of $H^{n}(\mathcal{N}, \mathcal{M})$ can be restricted to $n \geqslant 2$.

Theorem 4.1. Let $\mathcal{N} \subseteq \mathcal{M}$ be an inclusion of type $\mathrm{II}_{1}$ factors of finite index on a separable Hilbert space and suppose that $\mathcal{N}$ has a Cartan subalgebra $\mathcal{A}$. Then $H^{n}(\mathcal{N}, \mathcal{M})=0$ for $n \geqslant 2$.

Proof. Let $\mathcal{U} \subseteq \mathcal{N}$ be the group of normalizing unitaries for $\mathcal{A}$. Then $\operatorname{Alg}(\mathcal{U})=\operatorname{Span}(\mathcal{U})$, and the norm closure of $\operatorname{Alg}(\mathcal{U})$ is a $C^{*}$-algebra denoted by $C^{*}(\mathcal{U})$. Now fix $n \geqslant 2$. As in the proof of Theorem 5.1, [27], it suffices to consider an $\mathcal{R}$-multimodular separately normal cocycle $\theta: \mathcal{N}^{n} \rightarrow \mathcal{M}$ and show that its restriction to $C^{*}(\mathcal{U})$ is a coboundary.

Fix $u_{1}, \ldots, u_{n-1} \in \mathcal{U}$, and define $\mu: \mathcal{N} \rightarrow \mathcal{M}$ by

$$
\begin{equation*}
\mu(x)=\theta\left(u_{1}, \ldots, u_{n-1}, x\right), \quad x \in \mathcal{N} \tag{4.1}
\end{equation*}
$$

We first show that $\mu$ is completely bounded. Since $\mu$ is normal and right $\mathcal{R}$-modular, it follows from [27], Proposition 4.2, that $\mu$ is row bounded and

$$
\begin{equation*}
\|\mu\| \leqslant\|\mu\|_{\mathrm{r}} \leqslant \sqrt{2}\|\mu\| \tag{4.2}
\end{equation*}
$$

Let $\beta_{i}$ be the $*$-automorphism of $\mathcal{A}$ defined by

$$
\begin{equation*}
\beta_{i}(x)=u_{i}^{*} x u_{i}, \quad x \in \mathcal{A}, 1 \leqslant i \leqslant n-1, \tag{4.3}
\end{equation*}
$$

and define

$$
\begin{equation*}
\alpha_{j}=\beta_{j} \beta_{j-1} \cdots \beta_{2} \beta_{1} \in \operatorname{Aut}(\mathcal{A}), \quad 1 \leqslant j \leqslant n-1 \tag{4.4}
\end{equation*}
$$

The $\mathcal{A}$-modularity of $\theta$ implies that

$$
\begin{align*}
a \mu(x) & =a \theta\left(u_{1}, \ldots, u_{n-1}, x\right)=\theta\left(a u_{1}, \ldots, u_{n-1}, x\right)  \tag{4.5}\\
& =\theta\left(u_{1} \beta_{1}(a), u_{2}, \ldots, u_{n-1}, x\right)=\theta\left(u_{1}, \beta_{1}(a) u_{2}, \ldots, u_{n-1}, x\right),
\end{align*}
$$

and repetition of this argument in (4.5) leads to

$$
\begin{equation*}
a \mu(x)=\mu\left(\alpha_{n-1}(a) x\right), \quad x \in \mathcal{N}, a \in \mathcal{A} \tag{4.6}
\end{equation*}
$$

It then follows from (4.6) and Corollary 3.5 that $\mu$ is completely bounded and

$$
\begin{equation*}
\|\mu\|_{\mathrm{cb}} \leqslant\left(2[\mathcal{M}: \mathcal{N}]^{2}\right)\|\mu\|_{\mathrm{r}} \leqslant\left(2 \sqrt{2}[\mathcal{M}: \mathcal{N}]^{2}\right)\|\mu\| \tag{4.7}
\end{equation*}
$$

These inequalities are a consequence of (3.30) and (4.2). Thus $\mu \in \mathcal{S}$ (see Theorem 3.2).

By linearity, all maps of the form

$$
\begin{equation*}
x \mapsto \theta\left(y_{1}, \ldots, y_{n-1}, x\right) \tag{4.8}
\end{equation*}
$$

for $y_{i} \in \operatorname{Alg}(\mathcal{U})$ lie in $\mathcal{S}$, and the same is true for $y_{i} \in C^{*}(\mathcal{U})$ since $\mathcal{S}$ is $\|\cdot\|_{\mathrm{r}}$-closed and $\|\cdot\|$ and $\|\cdot\|_{\mathrm{r}}$ are equivalent on these maps. The modular properties of $\mathcal{S}$ show that every map (with $x$ as the variable) in the cocycle equation

$$
\begin{align*}
& y_{1} \theta\left(y_{2}, \ldots, y_{n}, x\right)+\sum_{i=1}^{n-1}(-1)^{i} \theta\left(y_{1}, \ldots, y_{i-1}, y_{i} y_{i+1}, y_{i+2}, \ldots, y_{n}, x\right)  \tag{4.9}\\
& \quad+(-1)^{n} \theta\left(y_{1}, \ldots, y_{n-1}, y_{n} x\right)+(-1)^{n+1} \theta\left(y_{1}, \ldots, y_{n}\right) x=0
\end{align*}
$$

for $y_{i} \in C^{*}(\mathcal{U})$, lies in $\mathcal{S}$ and so $\rho$ may be applied to (4.9). By Theorem 3.2, there exists an element $\psi\left(y_{1}, \ldots, y_{n-1}\right) \in \mathcal{M}$ such that

$$
\begin{equation*}
\rho\left(\theta\left(y_{1}, \ldots, y_{n-1}, x\right)\right)=\psi\left(y_{1}, \ldots, y_{n-1}\right) x, \quad x \in \mathcal{N} \tag{4.10}
\end{equation*}
$$

and the estimate

$$
\begin{equation*}
\left\|\psi\left(y_{1}, \ldots, y_{n-1}\right)\right\| \leqslant \sqrt{2}\left\|y_{1}\right\| \cdots\left\|y_{n-1}\right\| \tag{4.11}
\end{equation*}
$$

is immediate from (3.12) and (4.2). The $(n-1)$-linearity of $\psi$ results from the $n$-linearity of $\theta$ and the linearity of $\rho$. Using Theorem 3.2 once more, $\rho$ transforms (4.9) to

$$
\begin{align*}
& y_{1} \psi\left(y_{2}, \ldots, y_{n-1}\right) x+\sum_{i=1}^{n-1}(-1)^{i} \psi\left(y_{1}, \ldots, y_{i-1}, y_{i} y_{i+1}, \ldots, y_{n}\right) x  \tag{4.12}\\
& +(-1)^{n} \psi\left(y_{1}, \ldots, y_{n-1}\right) y_{n} x+(-1)^{n+1} \theta\left(y_{1}, \ldots, y_{n}\right) x=0
\end{align*}
$$

for $y_{i} \in C^{*}(\mathcal{U}), x \in \mathcal{N}$. Setting $x=1$ in (4.12) shows that the restriction of $\theta$ to $C^{*}(\mathcal{U})$ is the coboundary $\partial\left((-1)^{n} \psi\right)$, completing the proof.

We recall from [25] that the completely bounded cohomology groups $H_{\mathrm{cb}}^{n}(\mathcal{N}, \mathcal{M})$ are defined just as are $H^{n}(\mathcal{N}, \mathcal{M})$, but with the added requirement that all multilinear maps be completely bounded.

Theorem 4.2. Let $\mathcal{N} \subseteq \mathcal{M}$ be a finite index inclusion of von Neumann algebras. Then $H_{\mathrm{cb}}^{n}(\mathcal{N}, \mathcal{M})=0$ for $n \geqslant 1$.

Proof. This is identical to the last step in the preceding proof, using the projection $\rho$ of Theorem 3.3.

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